

# NAG C Library Function Document

## nag\_zero\_nonlin\_eqns\_1 (c05tbc)

### 1 Purpose

nag\_zero\_nonlin\_eqns\_1 (c05tbc) finds a solution of a system of nonlinear equations by a modification of the Powell hybrid method.

### 2 Specification

```
#include <nag.h>
#include <nagc05.h>

void nag_zero_nonlin_eqns_1 (Integer n, double x[], double fvec[],
    void (*)(Integer n, const double x[], double fvec[], Integer *userflag,
        Nag_User *comm),
    double xtol, Nag_User *comm, NagError *fail)
```

### 3 Description

The system of equations is defined as:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad \text{for } i = 1, 2, \dots, n.$$

nag\_zero\_nonlin\_eqns\_1 (c05tbc) is based upon the MINPACK routine HYBRD1 (Moré *et al.* (1980)). It chooses the correction at each step as a convex combination of the Newton and scaled gradient directions. Under reasonable conditions this guarantees global convergence for starting points far from the solution and a fast rate of convergence. The Jacobian is updated by the rank-1 method of Broyden. At the starting point the Jacobian is approximated by forward differences, but these are not used again until the rank-1 method fails to produce satisfactory progress. For more details see Powell (1970).

### 4 References

Moré J J, Garbow B S and Hillstom K E (1980) User guide for MINPACK-1 *Technical Report ANL-80-74* Argonne National Laboratory

Powell M J D (1970) A hybrid method for nonlinear algebraic equations *Numerical Methods for Nonlinear Algebraic Equations* (ed P Rabinowitz) Gordon and Breach

### 5 Arguments

- 1: **n** – Integer *Input*  
*On entry:* the number of equations,  $n$ .  
*Constraint:*  $n > 0$ .
- 2: **x[n]** – double *Input/Output*  
*On entry:* an initial guess at the solution vector.  
*On exit:* the final estimate of the solution vector.
- 3: **fvec[n]** – double *Output*  
*On exit:* the function values at the final point,  $\mathbf{x}$ .
- 4: **f** – function, supplied by the user *External Function*  
**f**, supplied by the user, must return the values of the  $f_i$  at a point  $x$ .

Its specification is:

```
void f (Integer n, const double x[], double fvec[], Integer *userflag,
      Nag_User *comm)
```

1:    **n** – Integer *Input*  
*On entry:* the number of equations, *n*.

2:    **x[n]** – const double *Input*  
*On entry:* the components of the point *x* at which the functions must be evaluated.

3:    **fvec[n]** – double *Output*  
*On exit:* the function values  $f_i(x)$  (unless **userflag** is set to a negative value by **f**).

4:    **userflag** – Integer \* *Input/Output*  
*On entry:* **userflag** > 0.  
*On exit:* in general, **userflag** should not be reset by **f**. If, however, the user wishes to terminate execution (perhaps because some illegal point **x** has been reached), then **userflag** should be set to a negative integer. This value will be returned through **fail.errnum**.

5:    **comm** – Nag\_User \*  
 Pointer to a structure of type **Nag\_User** with the following member:  
**p** – Pointer  
*On entry/on exit:* the pointer **comm** → **p** should be cast to the required type, e.g. `struct user *s = (struct user *)comm→p`, to obtain the original object's address with appropriate type. (See the argument **comm** below.)

- 5:    **xtol** – double *Input*  
*On entry:* the accuracy in **x** to which the solution is required.  
*Suggested value:* the square root of the *machine precision*.  
*Constraint:* **xtol** ≥ 0.0.
- 6:    **comm** – Nag\_User \*  
 Pointer to a structure of type **Nag\_User** with the following member:  
**p** – Pointer  
*On entry/on exit:* the pointer **p**, of type Pointer, allows the user to communicate information to and from the user-defined function **f**(). An object of the required type should be declared by the user, e.g. a structure, and its address assigned to the pointer **p** by means of a cast to Pointer in the calling program, e.g. `comm.p = (Pointer)&s`. The type pointer will be void \* with a C compiler that defines void \* and char \* otherwise.
- 7:    **fail** – NagError \* *Input/Output*  
 The NAG error parameter, see the Essential Introduction.

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

**NE\_INT\_ARG\_LE**

On entry, **n** must not be less than or equal to 0: **n** =  $\langle value \rangle$ .

**NE\_NO\_IMPROVEMENT**

The iteration is not making good progress.

This failure exit may indicate that the system does not have a zero, or that the solution is very close to the origin (see Section 7). Otherwise, rerunning `nag_zero_nonlin_eqns_1` (c05tbc) from a different starting point may avoid the region of difficulty.

**NE\_REAL\_ARG\_LT**

On entry, **xtol** must not be less than 0.0: **xtol** =  $\langle value \rangle$ .

**NE\_TOO\_MANY\_FUNC\_EVAL**

There have been at least  $200 \times (\mathbf{n} + 1)$  evaluations of **f**.

Consider restarting the calculation from the point held in **x**.

**NE\_USER\_STOP**

User requested termination, user flag value =  $\langle value \rangle$ .

**NE\_XTOL\_TOO\_SMALL**

No further improvement in the solution is possible. **xtol** is too small: **xtol** =  $\langle value \rangle$ .

**7 Accuracy**

If  $\hat{x}$  is the true solution, `nag_zero_nonlin_eqns_1` (c05tbc) tries to ensure that

$$\|x - \hat{x}\| \leq \mathbf{xtol} \times \|\hat{x}\|.$$

If this condition is satisfied with  $\mathbf{xtol} = 10^{-k}$ , then the larger components of  $x$  have  $k$  significant decimal digits. There is a danger that the smaller components of  $x$  may have large relative errors, but the fast rate of convergence of `nag_zero_nonlin_eqns_1` (c05tbc) usually avoids this possibility.

If **xtol** is less than *machine precision*, and the above test is satisfied with the *machine precision* in place of **xtol**, then the function exits with **NE\_XTOL\_TOO\_SMALL**.

**Note:** this convergence test is based purely on relative error, and may not indicate convergence if the solution is very close to the origin.

The test assumes that the functions are reasonably well behaved. If this condition is not satisfied, then `nag_zero_nonlin_eqns_1` (c05tbc) may incorrectly indicate convergence. The validity of the answer can be checked, for example, by rerunning `nag_zero_nonlin_eqns_1` (c05tbc) with a tighter tolerance.

**8 Further Comments**

The time required by `nag_zero_nonlin_eqns_1` (c05tbc) to solve a given problem depends on  $n$ , the behaviour of the functions, the accuracy requested and the starting point. The number of arithmetic operations executed by `nag_zero_nonlin_eqns_1` (c05tbc) to process each call of **f** is about  $11.5 \times n^2$ . Unless **f** can be evaluated quickly, the timing of `nag_zero_nonlin_eqns_1` (c05tbc) will be strongly influenced by the time spent in **f**.

Ideally the problem should be scaled so that at the solution the function values are of comparable magnitude.

## 9 Example

To determine the values  $x_1, \dots, x_9$  which satisfy the tridiagonal equations:

$$\begin{array}{rcccccc} (3 - 2x_1)x_1 & - & 2x_2 & & & = & -1 \\ -x_{i-1} & + & (3 - 2x_i)x_i & - & 2x_{i+1} & = & -1, \quad i = 2, 3, \dots, 8 \\ & & -x_8 & + & (3 - 2x_9)x_9 & = & -1. \end{array}$$

### 9.1 Program Text

```

/* nag_zero_nonlin_eqns_1 (c05tbc) Example Program.
 *
 * Copyright 1998 Numerical Algorithms Group.
 *
 * Mark 5, 1998.
 * Mark 7 revised, 2001.
 * Mark 8 revised, 2004.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <math.h>
#include <nagc05.h>
#include <nagx02.h>

#ifdef __cplusplus
extern "C" {
#endif
    static void f(Integer n, double x[], double fvec[], Integer *userflag,
                  Nag_User *comm);
#ifdef __cplusplus
}
#endif

int main(void)
{
    Integer exit_status=0, i, j, n=9;
    NagError fail;
    Nag_User comm;
    double *fvec=0, *x=0, xtol;

    INIT_FAIL(fail);

    Vprintf("nag_zero_nonlin_eqns_1 (c05tbc) Example Program Results\n");
    if (n>0)
    {
        if ( !( fvec = NAG_ALLOC(n, double) ) ||
            !( x = NAG_ALLOC(n, double) ) )
        {
            Vprintf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
    }
    else
    {
        Vprintf("Invalid n.\n");
        exit_status = 1;
        return exit_status;
    }

    /* The following starting values provide a rough solution. */
    for (j=0; j<n; j++)
        x[j] = -1.0;
    /* nag_machine_precision (x02ajc).
     * The machine precision
     */

```

```

xtol = sqrt(X02AJC);
/* nag_zero_nonlin_eqns_1 (c05tbc).
 * Solution of a system of nonlinear equations (function
 * values only), thread-safe
 */
nag_zero_nonlin_eqns_1(n, x, fvec, f, xtol, &comm, &fail);
if (fail.code == NE_NOERROR)
{
    Vprintf("Final approximate solution\n\n");
    for (j=0; j<n; j++)
        Vprintf("%12.4f%s",x[j], (j%3==2 || j==n-1) ? "\n" : " ");
}
else
{
    Vprintf("Error from nag_zero_nonlin_eqns_1 (c05tbc).\n%s\n",
        fail.message);
    if (fail.code == NE_TOO_MANY_FUNC_EVAL ||
        fail.code == NE_XTOL_TOO_SMALL ||
        fail.code == NE_NO_IMPROVEMENT)
    {
        Vprintf("Approximate solution\n\n");
        for (i=0; i<n; i++)
            Vprintf("%12.4f%s",x[i], (i%3==2 || i==n-1) ? "\n" : " ");
        exit_status = 2;
    }
}
END:
if (fvec) NAG_FREE(fvec);
if (x) NAG_FREE(x);
return exit_status;
}
static void f(Integer n, double x[], double fvec[], Integer *userflag,
              Nag_User *comm)
{
    Integer k;

    for (k=0; k<n; ++k)
    {
        fvec[k] = (3.0-x[k]*2.0)*x[k]+1.0;
        if (k>0)
            fvec[k] -= x[k-1];
        if (k<n-1)
            fvec[k] -= x[k+1]*2.0;
    }
}

```

## 9.2 Program Data

None.

## 9.3 Program Results

nag\_zero\_nonlin\_eqns\_1 (c05tbc) Example Program Results  
 Final approximate solution

-0.5707	-0.6816	-0.7017
-0.7042	-0.7014	-0.6919
-0.6658	-0.5960	-0.4164

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